Competition



Commensalism

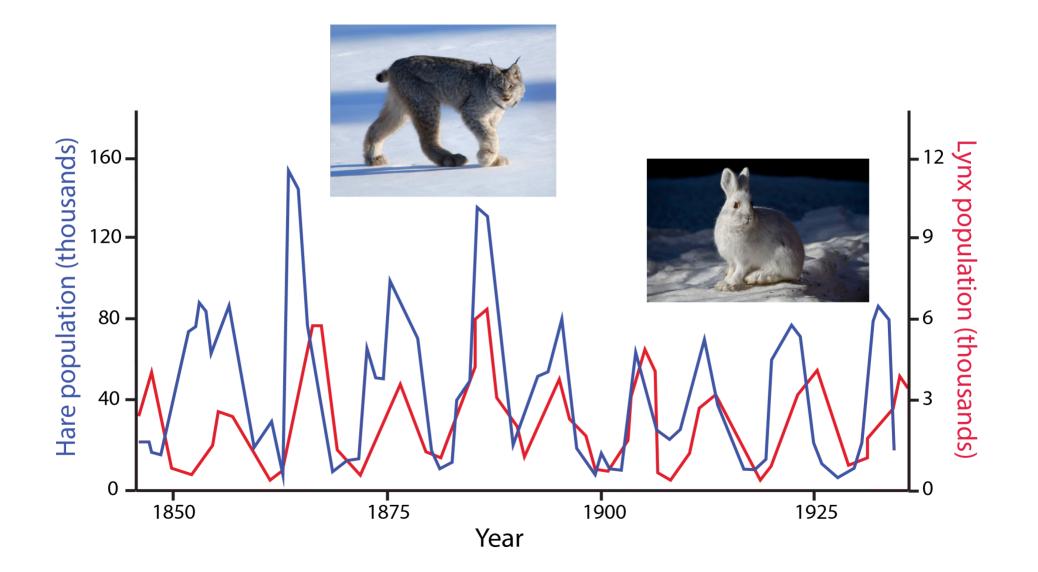
Predation

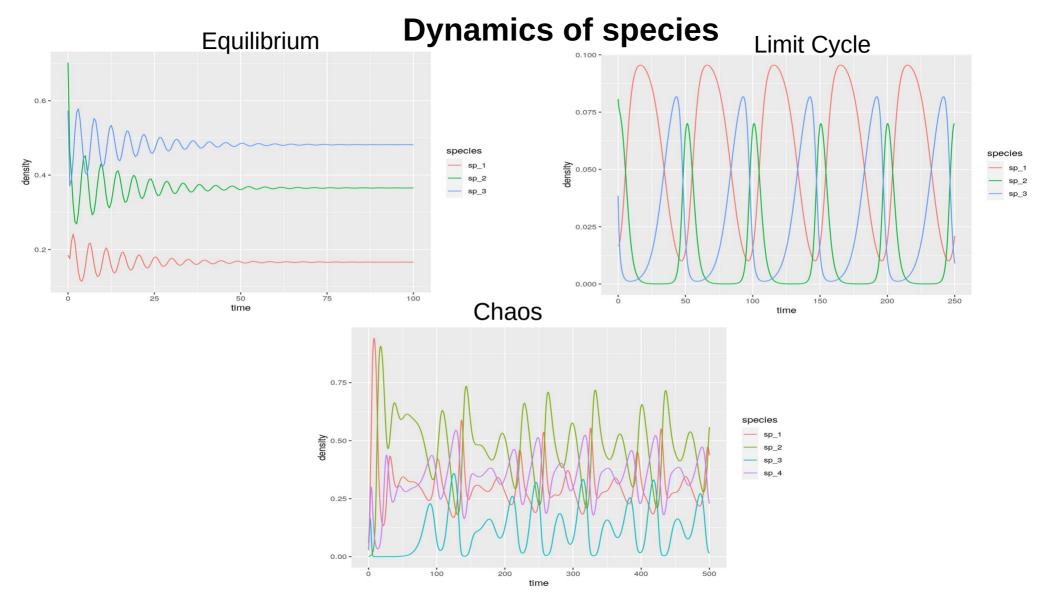


Mutualism

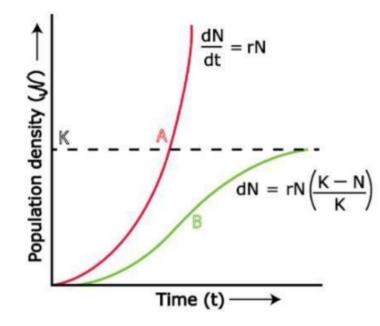




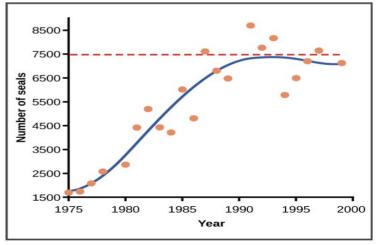




Modeling population growth rates







General models for single species populations and analysis of local equilibrium stability

Growth equation for single population : $\frac{dN}{dt} = f(N)$

Algebraic and geometric analysis of local equilibrium stability

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Equilibrium point N_0 satisfy f(N_0) = 0
x(t) = N(t) - N_0
```

$$\frac{dx}{dt} = f'(N_0) * x + f''(N_0) * x^2/2 + f'''(N_0) * x^3/6 + \dots$$

We obtain an approximate linear differential equation for the perturbation x(t):

$$\frac{dx}{dt} \approx f'(N_0) x$$

$$x(t) = x(0) e^{f'(N_0)t}$$
stable
$$f'(N_0) < 0$$
unstable
$$f'(N_0) > 0$$

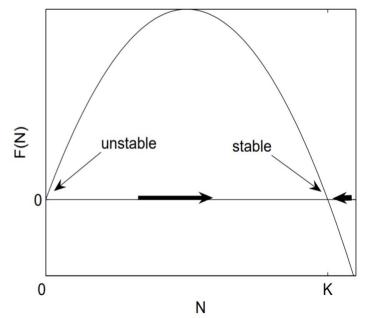
In the case of the logistic equation:

$$f'(N) = r\left(1 - \frac{2N}{K}\right)$$
 (logistic equation)

Therefore,

 $N_0 = 0$ Unstable equilibrium

 $N_0 = K$ Stable equilibrium



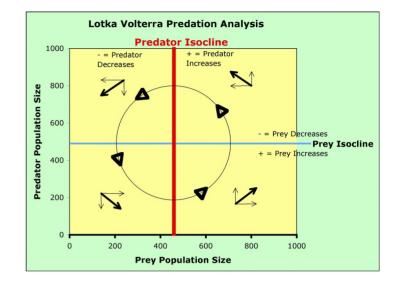
Two-species Lotka-Volterra systems

Predator-Prey Systems

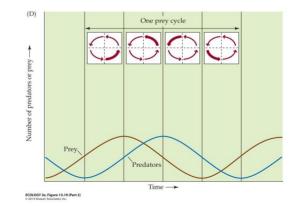
Prey :
$$\frac{dN}{dt} = rN - aNP$$

Predator : $\frac{dP}{dt} = abNP - mP$

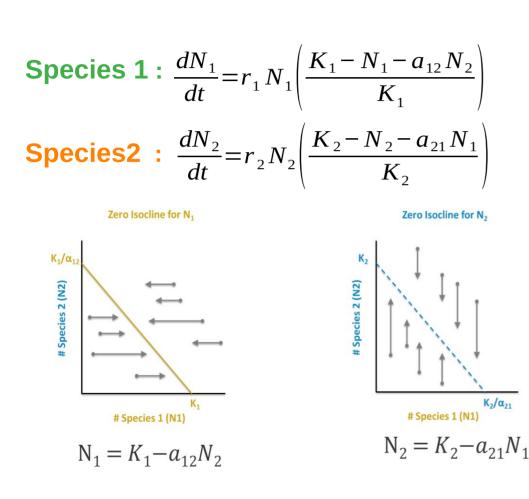
- N = number of prey individuals r = prey per capita rate increase a = capture efficiency P = number of predator individuals
- m = mortality rate
- b = capture efficiency



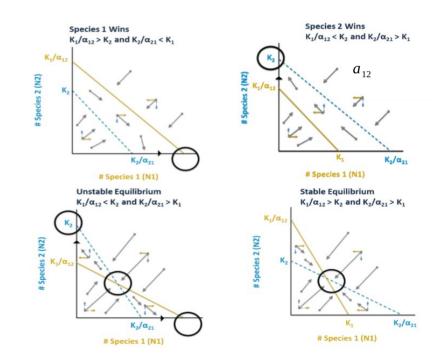
Oscillations: a mathematical model



Interspecific competition : Lotka-Volterra Model

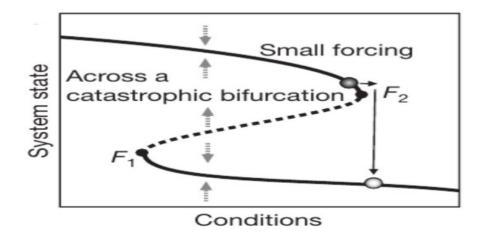


- a_{12} : The effect an individual of species 2 has on the population growth of species 1
- a_{21} : The effect an individual of species 1 has on the population growth of species 2



What is critical transition or tipping ?

In complex systems, "tipping" or "critical transitions" are sudden, large, often irreversible and usually unexpected changes in the state of a system, precipitated under the influence of small stochastic perturbations. Stochastic Dynamical System



- Scheffer, M., Bascompte, J., Brock, W.A., Brovkin, V., Carpenter, S.R., Dakos, V., Held, H., Van Nes, E.H., Rietkerk, M. and Sugihara, G., 2009. Early-warning signals for critical transitions. Nature, 461(7260), pp.53-59..

$$\frac{dN_{1}}{dt} = r_{1} N_{1} \left(\frac{K_{1} - N_{1} + a_{12} N_{2}}{K_{1}} \right) \\
\frac{dN_{2}}{dt} = r_{2} N_{2} \left(\frac{K_{2} - N_{2} + a_{21} N_{1}}{K_{2}} \right)$$

Generalized Lotka-Volterra Model

$$\frac{dN_i}{dt} = N_i \left(r_i + \sum_{j=1}^n a_{ij} N_j \right)$$

Mutualistic (+/+) interaction implies both $a_{ij}>0$ and $a_{ji}>0$

Competitive (-/-) interaction implies both $a_{ij} < 0$ and $a_{ji} < 0$

$$\begin{split} & \textbf{Stability of an equilibrium} \\ & \frac{dN_i}{dt} = f_i \big(N(t) \big) \\ & \frac{dN_i}{dt} \bigg|_{N_0} = f_i \big(N_0 \big) = 0 \qquad \forall i \\ & \Delta N(0) = N(0) - N_0 \\ & f(\Delta N(0)) = f(N_0) + J|_{N_0} \Delta N(0) + \dots \\ & J_{ij} = \frac{\partial f_i(N)}{\partial N_j} \\ & \textbf{We obtain the so-called "community matrix"} \quad M = J|_{N_0} \\ & \lambda_{max} < 0 \qquad \longrightarrow N_0 \text{ is stable} \\ & \lambda_{max} > 0 \qquad \longrightarrow N_0 \text{ is unstable} \end{split} \quad \begin{aligned} & \text{For the GLV} \\ & J_{ij} = \frac{\partial f_i(N)}{\partial N_j} \\ & J_{ii} = \frac{\partial f_i(N)}{\partial$$

For the GLV model, the Jacobian is easy to compute:

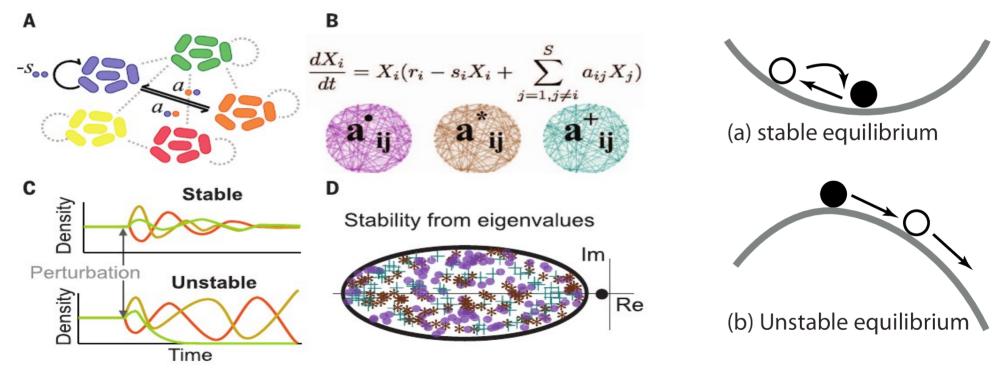
$$J_{ij} = \frac{\partial f_i(N)}{\partial N_j} = a_{ij}N_i$$
$$J_{ii} = \frac{\partial f_i}{\partial N_j} = r_i + \sum_j a_{ij}N_j + a_{ii}N_i$$

Where nonzero equilibrium point is

$$r_i + \sum_j a_{ij} N_j = 0$$

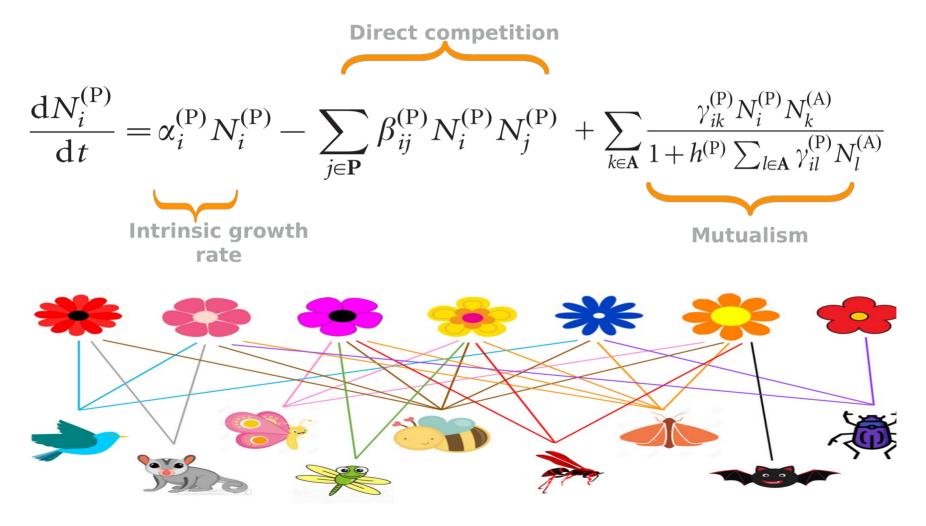
What is Stability?

Faster the recovery implies higher system stability. Stability can be analyzed linearly, that is, by studying the eigenvalues of the

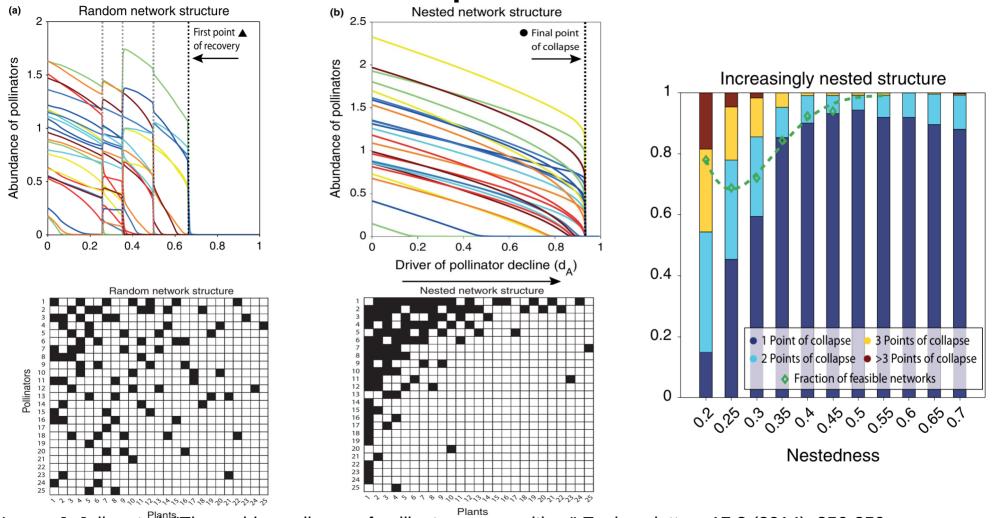


Coyte et al., The ecology of the microbiome: networks, competition, and stability, Science 350.6261 (2015): 663-666.

Mutualistic model

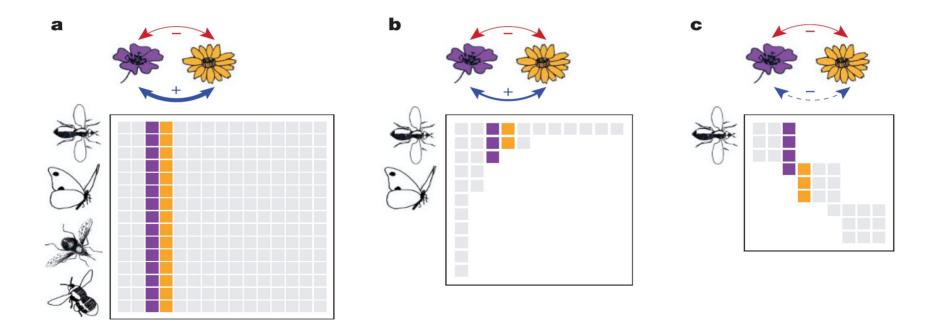


Sudden Collapse in Pollinator Networks



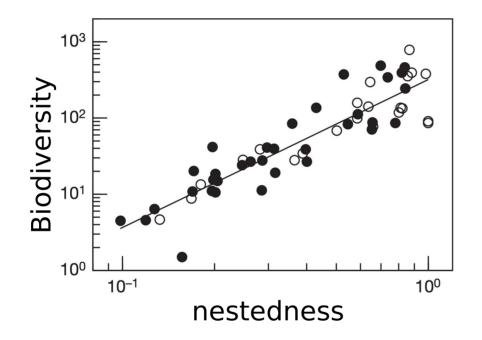
Lever, J. Jelle, et al. "The sudden collapse of pollinator communities." Ecology letters 17.3 (2014): 350-359.

$$C_{ij}^{(P)} = \delta_{ij} + \frac{1}{\bar{S}^{(P)}} + R\left(\frac{1}{\bar{S}^{(A)} + \bar{S}^{(A)}} n_i^{(P)} n_j^{(P)} - n_{ij}^{(P)}\right)$$

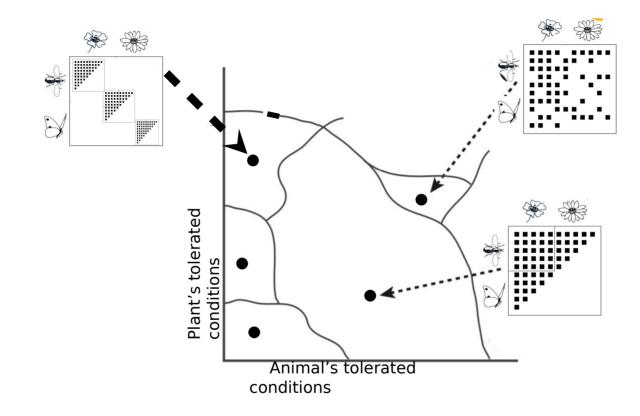


Bastolla, Fortuna, Pascual-García, Ferrera, Luque and Bascompte (2009). Nature 458: 1018-1020

Network structure increases robustness

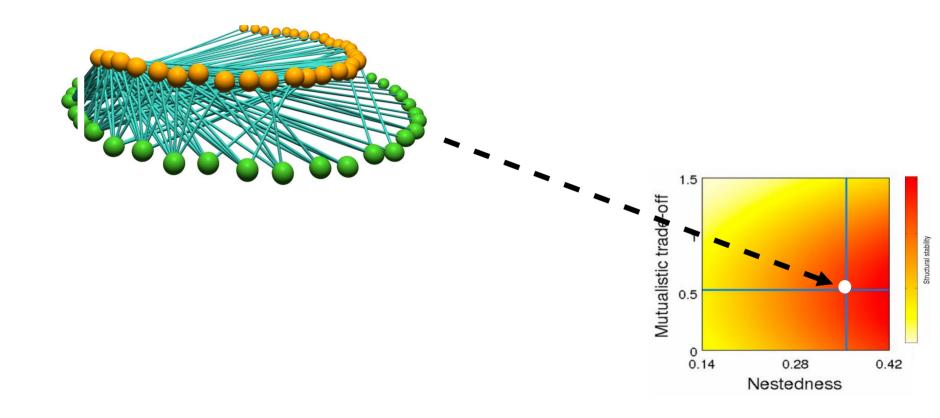


Bastolla, Fortuna, Pascual-García, Ferrera, Luque and Bascompte (2009). Nature 458: 1018-1020



Rohr, Saavedra, and Bascompte (2014). Science, 345: 1253497

Network structure increases robustness



Rohr, Saavedra, and Bascompte (2014). Science, 345: 1253497